

产品品号选型规则

26	□	□	□	□	-	□	-	□	-	□
电机系列	样式	步距	极性	步长编码		电压		行程		后缀
26000电机系列数字	C=固定轴电机 E=外部驱动电机 N=贯通轴电机	F=7.5° 步距角 E=15° 步距角	4=双极性(4线)	代码ID 例: 1=0.0254mm 2=0.0508mm 3=0.0127mm 4=0.1016mm		05=5V 12=12V		固定轴行程编号 例: 303=12.7mm (行程)		流水号
例: 26CF43-05-303-001										

26	□	□	□	□	-	□	-	□	-	□
Motor series	style	Step length	Coils	Code ID		Voltage		stroke		Suffix
26=26000 (Series numbers represent approximate width of motor body)	C=Captive E=External Lin. N=Non-captive	F=7.5° E=15°	4=Bipolar (4 wire)	Code ID 1=.001-in (.0254) 2=.002-in (.0508) 3=.0005-in (.0127) 4=.004-in (.1016)		05=5V 12=12V		Captive Stroke Code 303=0.5-in		Serial number
例: 26CF43-05-303-001										

固定轴式电机行程代码

行程编号 stroke code	行程 (in) stroke	行程 (mm) stroke
302	0.5	12.7
303	0.7087	18
304	0.9843	25
305	1.2204	31

步长编码 Linear Travel / Step				
步进角度 Step Angle	导程mm	英寸 inches	步长mm	代码ID Code ID
7.5°	1.2192	0.001	0.0254	1
	2.4384	0.002	0.0508	2
	0.6096	0.0005	0.0127	3
	4.8768	0.004	0.1016	4
	9.7536	0.008	0.2032	5
	19.5072	0.016	0.4064	6
	0.9984	0.0008	0.0208	7
	1.9997	0.0016	0.04166	8
	3.9984	0.0032	0.0833	9
	7.9997	0.0065	0.16666	A
	0.7008	0.000574	0.0146	B
	0.3048	0.00025	0.00635	C
15°		0.001	0.0254	1
		0.002	0.0508	2
		0.004	0.1016	4

产品特性

产品品号 Part No.	贯通轴式 Non-captive	26NF4 (X) -V		26NE4 (X) -V	
	外驱轴式 External Lin.	26EF4 (X) -V		26EE4 (X) -V	
	固定轴式 Captive	26CF4 (X) -V		26CE4 (X) -V-	
极性 Wiring	单位 Units	双极性 (Bipolar)			
步进角度 Step Angle	度 Degree	7.5°		15°	
绕组电压 Winding Voltage	VDC	5	12	5	12
电流/相位 Current/Phase	A rms	0.385	0.16	0.385	0.16
电阻/相位 Resistance/Phase	ohms (Ω)	13	72	13	72
电感/相位 Inductance/Phase	mH	10.6	60	10.6	48
电源输入 Power Input	Watts	3.85			
转子惯性 Rotor Inertia	gcm ²	1.07			
绝缘等级 Insulation Class		B级 (75° 温升)			
重量 Weight	盎司 (克) oz (g)	1.74 (49)			
绝缘电阻 Insulation resistance	MΩ	20			

标准电机为B级，最高温度为130° C (F级为155° C)

**单极驱动器比双极驱动器的推力小约30%。

Standard motors are Class B rated for a maximum temperature of 130° C (155° C for Class F)

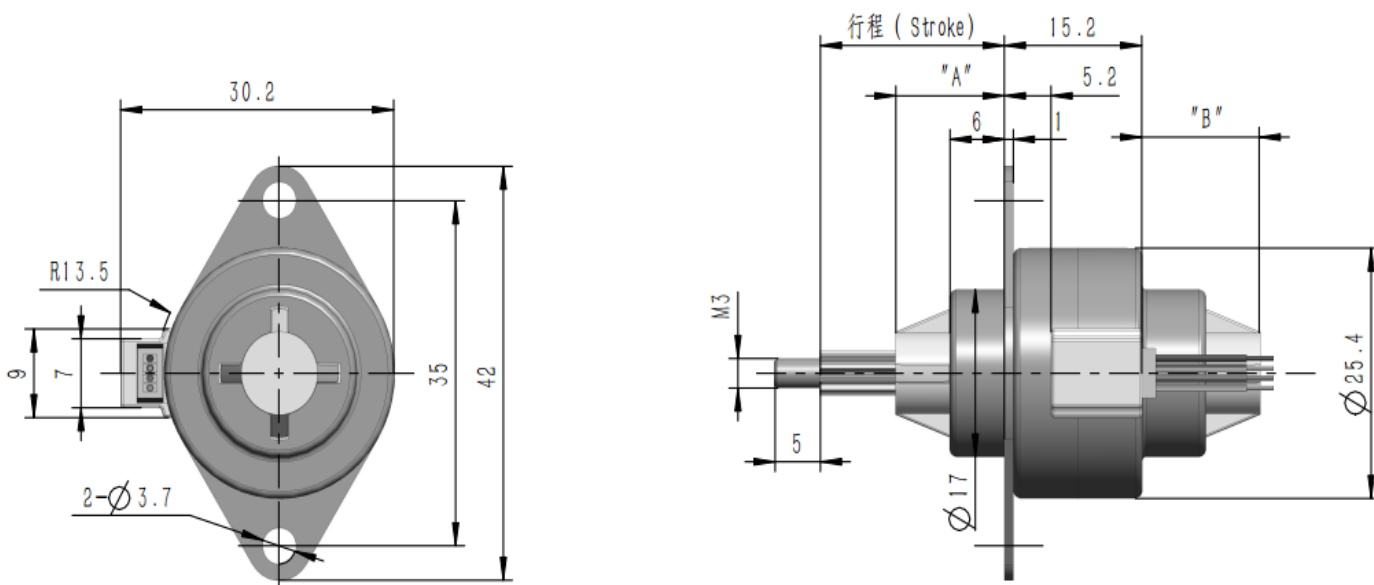
**Unipolar drive gives approximately 30% less thrust than bipolar drive.

尺寸参考图

Dimensional Drawings

固定轴式

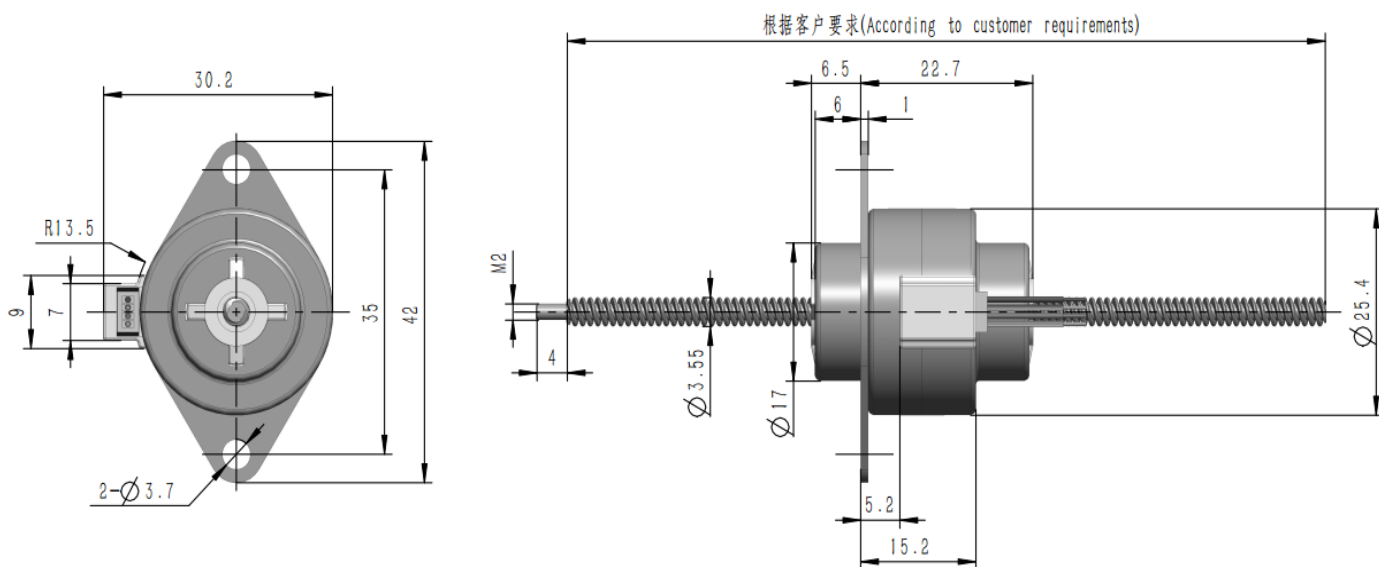
Captive



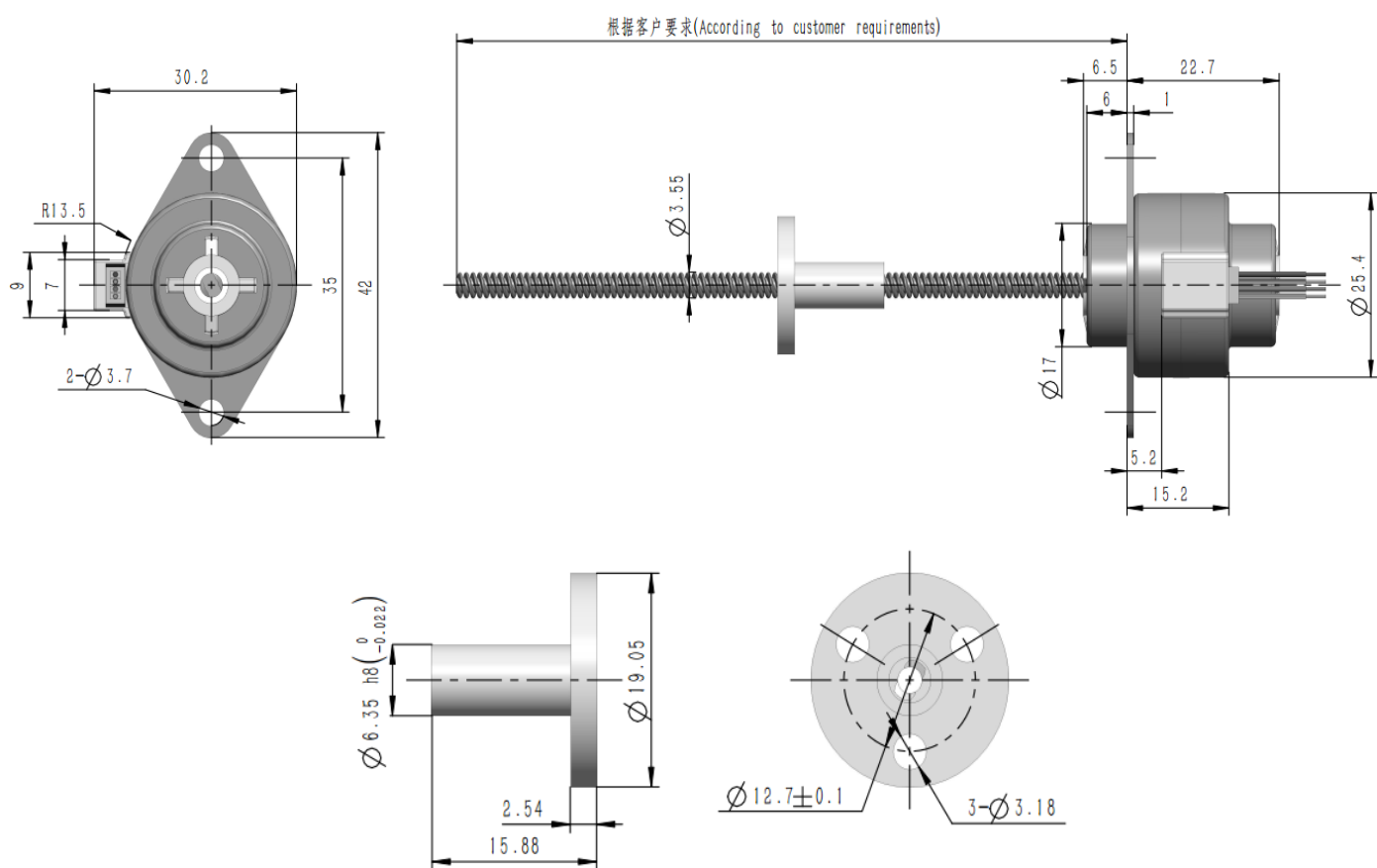
行程代码 stroke code	行程 (mm) stroke (mm)	尺寸A (mm) size A (mm)	尺寸B (mm) size B (mm)
302	12.7	11.99	12.99
303	18	17.28	18.28
304	25	24.26	25.26
305	31	30.25	31.25

贯通轴式

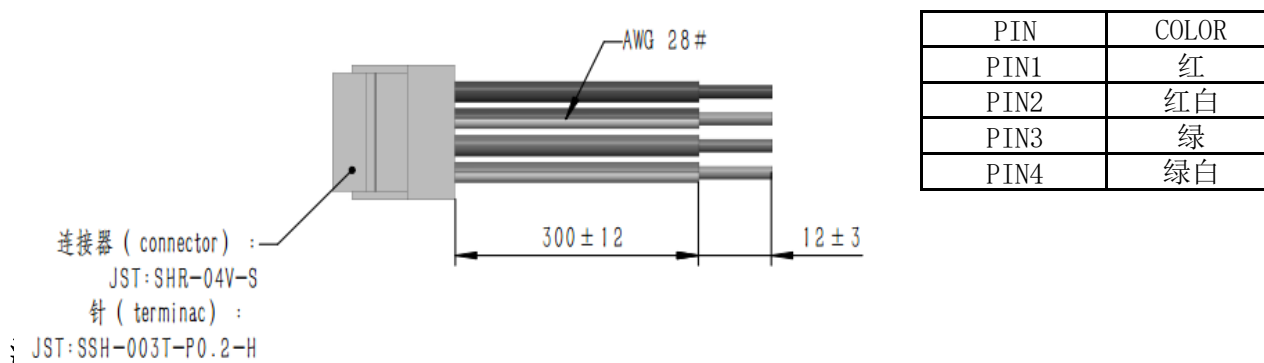
Non-captive



外部驱动式
External Lin.



电机引出线
Motor outlet

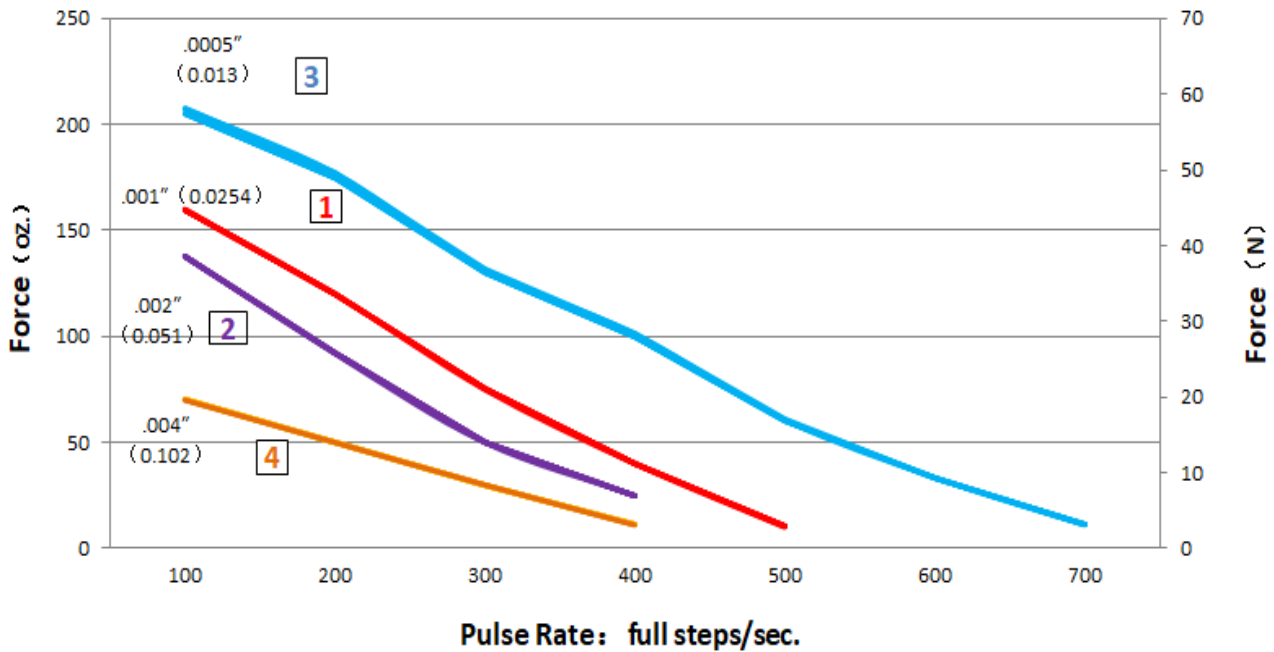


性能曲线

Performance Curves

推力与脉冲频率 (FORCE vs. PULSE RATE)

L/R驱动器, 双极性, 100%工作周期



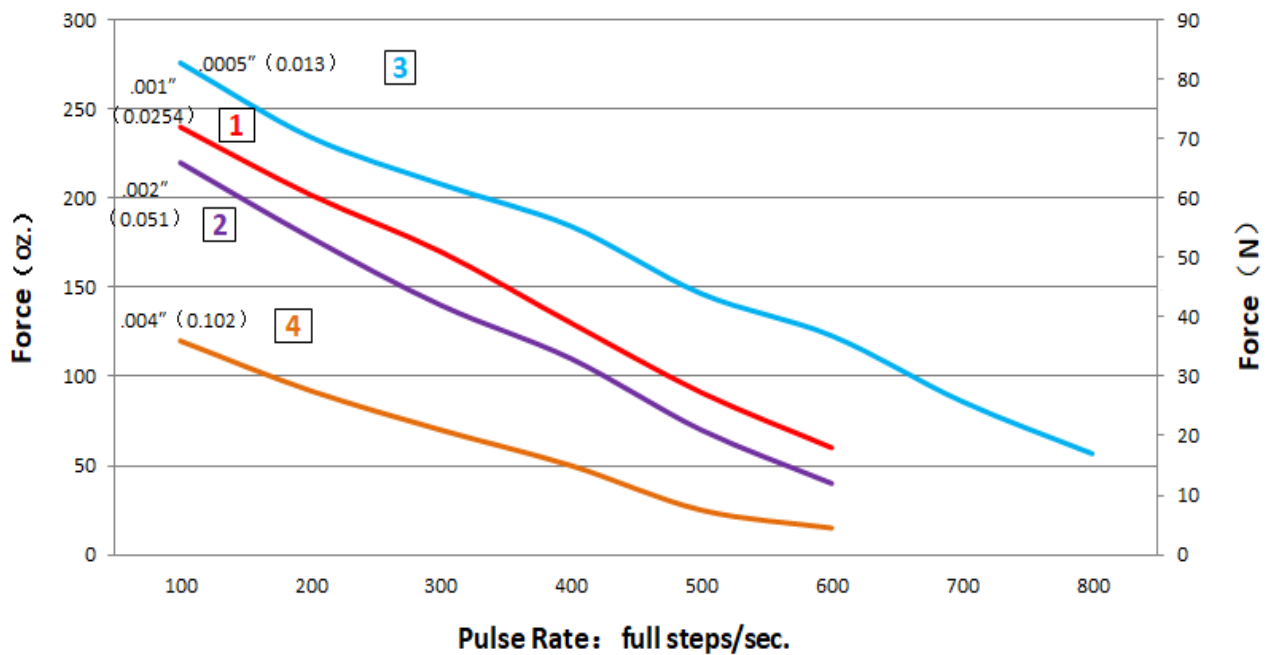
推力与脉冲频率 (FORCE vs. PULSE RATE)

L/R驱动器, 双极性, 25%工作周期

L/R Drive, Bipolar, 25% Duty Cycle

25%工作周期可通过特殊绕组或通过用两倍的额定电流运行标准电机获得。

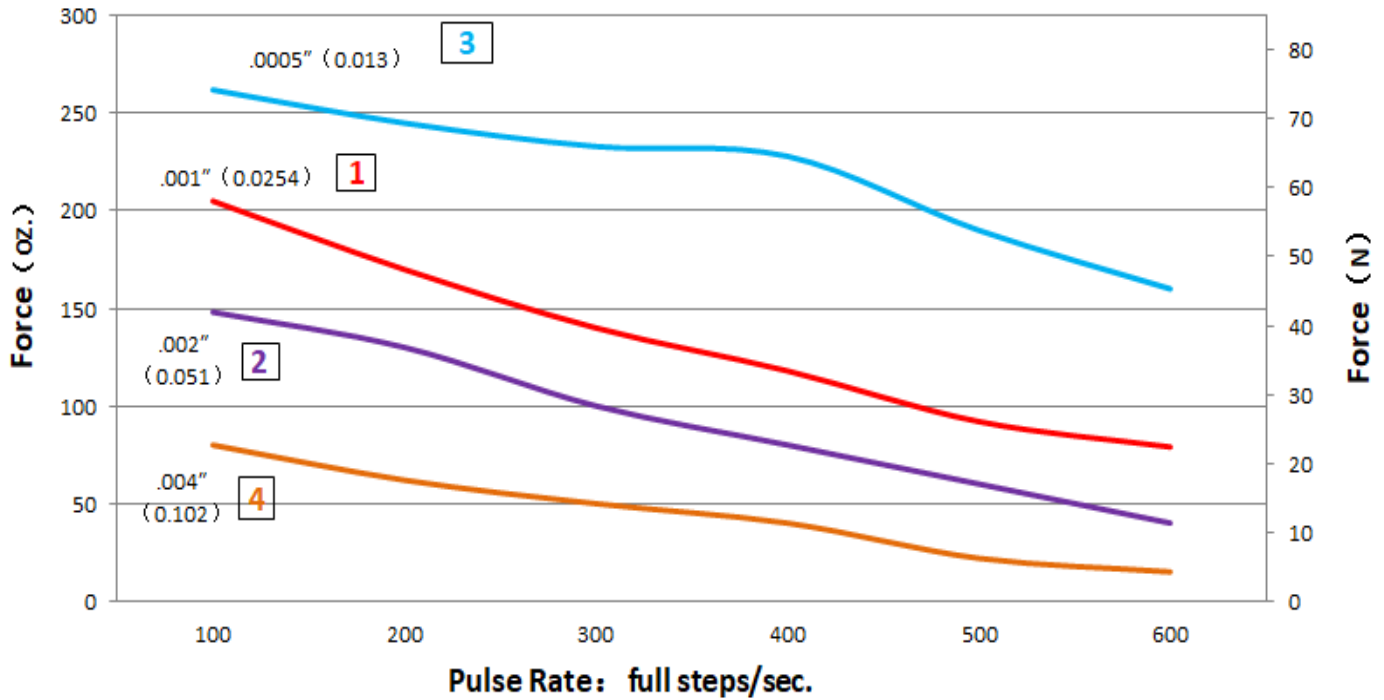
25% Duty Cycle is obtained by a special winding or by running a standard motor at double the rated current.



推力与脉冲频率 (FORCE vs. PULSE RATE)

斩波器驱动器，双极性，100%工作周期

Chopper Drive, Bipolar, 100% Duty Cycle



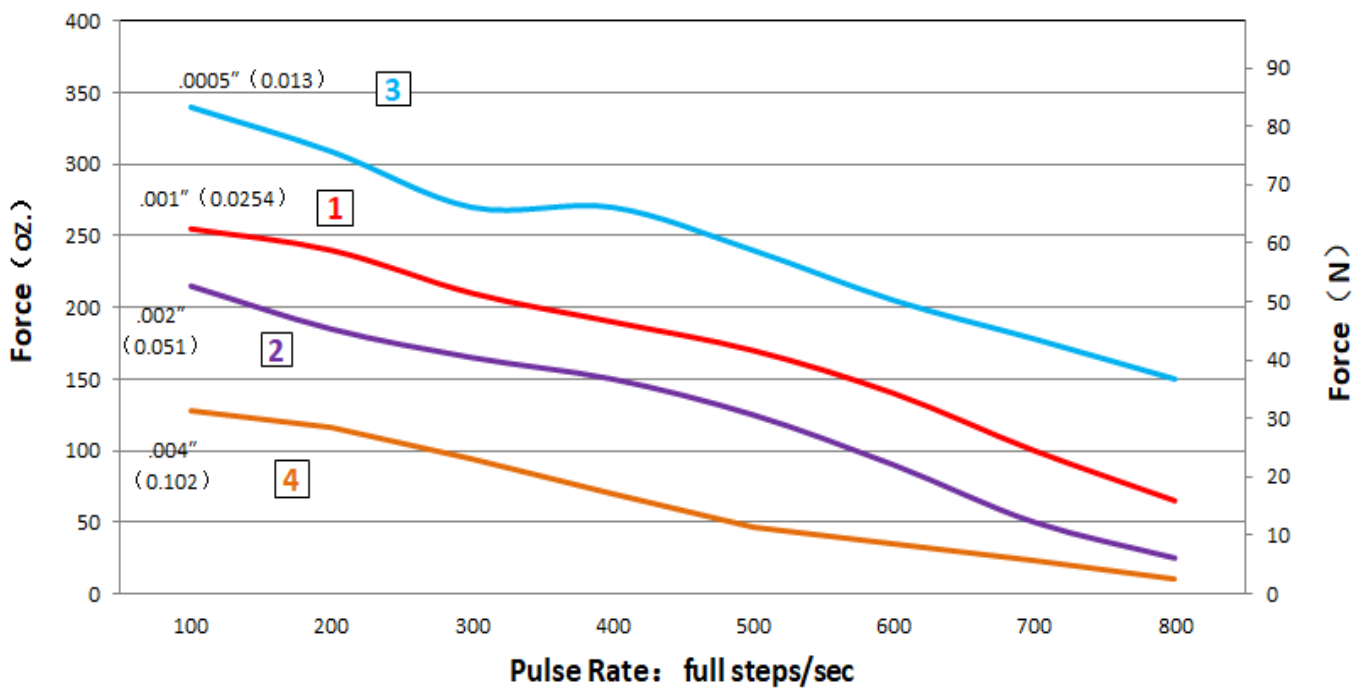
推力与脉冲频率 (FORCE vs. PULSE RATE)

斩波器驱动器，双极性，25%工作周期

Chopper Drive, Bipolar, 25% Duty Cycle

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注意：所有斩波驱动曲线都在5伏电机电压和40伏电源电压条件下创建。

增加脉冲频率时，设定一个加速度可以推动更大负载或者达到更高的速度，可以提高电机的性能。另外，设定减速度可以让电机停止时不会产生过冲。

使用L/R驱动器可以减小峰值力和速度，使用单极性驱动器会进一步减少30%的力。

NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.